
AdaBoost

AdaBoost, which stands for “**Ad**aptive **B**oosting”, is an ensemble learning algorithm that uses the boosting paradigm [1].

We will discuss AdaBoost for binary classification. That is, we assume that we are given a training set $S := (x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ where $\forall i, y_i \in \{-1, 1\}$ and a pool of hypothesis functions \mathcal{H} from which we are to pick T hypotheses in order to form an ensemble H . H then makes a decision using the individual hypotheses h_1, \dots, h_T in the ensemble as follows:

$$H(x) = \sum_{i=1}^T \alpha_i h_i(x) \quad (1)$$

That is, H uses a linear combination of the decisions of each of the h_i hypotheses in the ensemble. The AdaBoost algorithm sequentially chooses h_i from \mathcal{H} and assigns this hypothesis a weight α_i . We let H_t be the classifier formed by the first t hypotheses. That is,

$$\begin{aligned} H_t(x) &= \sum_{i=1}^t \alpha_i h_i(x) \\ &= H_{t-1}(x) + \alpha_t h_t(x) \end{aligned}$$

where $H_0(x) := 0$. That is, the empty ensemble will always output 0.

The idea behind the AdaBoost algorithm is that the t^{th} hypothesis will correct for the errors that the first $t - 1$ hypotheses make on the training set. More specifically, after we select the first $t - 1$ hypotheses, we determine which instances in S our $t - 1$ hypotheses perform poorly on and make sure that the t^{th} hypothesis performs well on these instances. The pseudocode for AdaBoost is described in Algorithm 1. A high-level overview of the algorithm is described below:

1. Initialize a training set distribution

At each iteration $1, \dots, T$ of the AdaBoost algorithm, we define a probability distribution \mathcal{D} over the training instances in S . We let \mathcal{D}_t be the probability distribution at the t^{th} iteration and $\mathcal{D}_t(i)$ be the probability assigned to the i^{th} training instance, $(x_i, y_i) \in S$, according to \mathcal{D}_t . As the algorithm proceeds, each iteration will design \mathcal{D}_t so that it assigns higher probability mass to instances that the first $t - 1$ hypotheses performed poorly on. That is, the worse the performance on x_i , the higher will be $\mathcal{D}_t(i)$.

At the onset of the algorithm, we set \mathcal{D}_1 to be the uniform distribution over the instances. That is,

$$\forall i \in \{1, 2, \dots, n\}, \mathcal{D}_1(i) := \frac{1}{n}$$

Algorithm 1 AdaBoost for binary classification

Precondition: A training set $S := (x_1, y_1), \dots, (x_n, y_n)$, hypothesis space \mathcal{H} , and number of iterations T .

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1 for  $i \in \{1, 2, \dots, n\}$  do
2    $\mathcal{D}_1(i) \leftarrow \frac{1}{n}$ 
3 end for
4  $H \leftarrow \emptyset$ 
5 for  $t = 1, \dots, T$  do
6    $h_t \leftarrow \operatorname{argmin}_{h \in \mathcal{H}} P_{i \sim \mathcal{D}_t}(h(x_i) \neq y_i)$   $\triangleright$  find good hypothesis on weighted training set
7    $\epsilon_t \leftarrow P_{i \sim \mathcal{D}_t}(h_t(x_i) \neq y_i)$   $\triangleright$  compute hypothesis's error
8    $\alpha_t \leftarrow \frac{1}{2} \ln\left(\frac{1-\epsilon_t}{\epsilon_t}\right)$   $\triangleright$  compute hypothesis's weight
9    $H \leftarrow H \cup \{(\alpha_t, h_t)\}$   $\triangleright$  add hypothesis to the ensemble
10  for  $i \in \{1, 2, \dots, n\}$  do  $\triangleright$  update training set distribution
11     $\mathcal{D}_{t+1}(i) \leftarrow \frac{\mathcal{D}_t(i) e^{-\alpha_t y_i h_t(x_i)}}{\sum_{j=1}^n \mathcal{D}_t(j) e^{-\alpha_t y_j h_t(x_j)}}$ 
12  end for
13 end for
14 return  $H$ 
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where n is the size of S .

2. Find a new hypothesis to add to the ensemble

At the t^{th} iteration, we search for a new hypothesis, h_t , that performs well on S assuming that instances are drawn from \mathcal{D}_t . By "performs well", we mean that h_t should have a low expected 0-1 loss on S under \mathcal{D}_t . That is

$$\begin{aligned} h_t &:= \operatorname{argmin}_{h \in \mathcal{H}} E_{i \sim \mathcal{D}_t}[\ell_{0-1}(h, x_i, y_i)] \\ &= \operatorname{argmin}_{h \in \mathcal{H}} P_{i \sim \mathcal{D}_t}(y_i \neq h(x_i)) \end{aligned}$$

We call this expected loss the "weighted loss" because the 0-1 loss is not computed on the instances in the training set directly, but rather on the *weighted* instances in the training set.

3. Assign the new hypothesis a weight

Once we compute h_t , we assign h_t a weight α_t based on its performance. More specifically, we give it the weight

$$\alpha_t := \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right) \quad (2)$$

where

$$\epsilon_t := P_{i \sim \mathcal{D}_t}(y_i \neq h_t(x_i))$$

. We will soon explain the theoretical justification of this precise weight assignment, but intuitively we see that the higher ϵ_t , the larger will be the denominator and the smaller the numerator in $\frac{1-\epsilon_t}{\epsilon_t}$ thus, the smaller will be $\frac{1}{2} \ln \left(\frac{1-\epsilon_t}{\epsilon_t} \right)$. Thus, if the new hypothesis, h_t , has a high error, ϵ_t , then we assign this hypothesis a smaller weight. That is, h_t will contribute less to the output of ensemble H .

4. Recompute the training set distribution

Once the new hypothesis is added to the ensemble, we recompute the training set distribution to assign each instance a probability proportional to how well the current ensemble H_t performs on the training set. We compute \mathcal{D}_{t+1} as follows:

$$\mathcal{D}_{t+1}(i) := \frac{\mathcal{D}_t(i) e^{-\alpha_t y_i h_t(x_i)}}{\sum_{j=1}^n \mathcal{D}_t(j) e^{-\alpha_t y_j h_t(x_j)}} \quad (3)$$

We will soon explain a theoretical justification for this precise probability assignment, but for now we can gain an intuitive understanding. Note the term $e^{-\alpha_t y_i h_t(x_i)}$. If $h_t(x_i) = y_i$, then $y_i h_t(x_i) = 1$ which means that $e^{-\alpha_t y_i h_t(x_i)} = e^{-\alpha_t}$. If, on the other hand, $h_t(x_i) \neq y_i$, then $y_i h_t(x_i) = -1$ which means that $e^{-\alpha_t y_i h_t(x_i)} = e^{\alpha_t}$. Thus, we see that $e^{-\alpha_t y_i h_t(x_i)}$ is smaller if the hypothesis's prediction agrees with the true value. That is, we assign higher probability to the i^{th} instance if h_t was wrong on x_i .

Repeat steps 2 through 4

Repeat steps 2 through 4 for $T - 1$ more iterations.

Derivation of AdaBoost from first principles

The AdaBoost algorithm can be viewed as an algorithm that searches for hypotheses of the form of Equation 1 in order to minimize the empirical loss under the **exponential loss function**:

$$\ell_{\text{exp}}(h, x, y) := e^{-yh(x)}$$

We note that there are many ways in which one might search for a hypothesis of the form of Equation 1 in order to minimize the exponential loss function. The AdaBoost algorithm performs this minimization using a sequential procedure such that, at iteration t , we are given H_{t-1} and our goal is to produce

$$H_t = H_{t-1} + \alpha_t h_t$$

where the new h_t and α_t minimizes the exponential loss of H_t on the training data. Theorem 1 shows that AdaBoost's choice of h_t minimizes the exponential loss of H_t over the training data. That is,

$$h_t = \operatorname{argmin}_{h \in \mathcal{H}} L_S(H_{t-1} + Ch)$$

where

$$L_S(H_{t-1} + Ch) := \frac{1}{n} \sum_{i=1}^n \ell_{\exp}(H_{t-1} + Ch, x, y)$$

and C is an arbitrary constant. Theorem 2 shows that once h_t is chosen, AdaBoost's choice of α_t then further minimizes the exponential loss of H_t over the training set. That is,

$$\alpha_t := \operatorname{argmin}_{\alpha} L_S(H_{t-1} + \alpha h_t)$$

Theorem 1 *The choice of h_t under AdaBoost,*

$$h_t := \operatorname{argmin}_{h \in \mathcal{H}} P_{i \sim \mathcal{D}_t}(y_i \neq h(x_i))$$

, minimizes the exponential-loss of H_t over the training set. That is, given an arbitrary constant C ,

$$h_t = \operatorname{argmin}_{h \in \mathcal{H}} L_S(H_{t-1} + Ch)$$

Proof:

$$h_t = \operatorname{argmin}_{h \in \mathcal{H}} L_S(H_{t-1} + Ch)$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n e^{-y_i[H_{t-1}(x_i) + Ch(x_i)]}$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n e^{-y_i H_{t-1}(x_i)} e^{-y Ch(x_i)}$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \frac{1}{n} \sum_{i=1}^n w_{t,i} e^{-y Ch(x_i)}$$

let $w_{t,i} := e^{-y_i H_{t-1}(x_i)}$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \sum_{i=1}^n w_{t,i} e^{-y Ch_t(x_i)}$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \left\{ \sum_{i:h(x_i)=y_i} w_{t,i} e^{-C} + \sum_{i:h(x_i) \neq y_i} w_{t,i} e^C \right\}$$

split the summation

$$= \operatorname{argmin}_{h \in \mathcal{H}} \left\{ \left(\sum_{i=1}^n w_{t,i} e^{-C} - \sum_{i:h(x_i) \neq y_i} w_{t,i} e^{-C} \right) + \sum_{i:h(x_i) \neq y_i} w_{t,i} e^C \right\}$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \left\{ \sum_{i=1}^n w_{t,i} e^{-C} + \sum_{i:h(x_i) \neq y_i} w_{t,i} (e^C - e^{-C}) \right\}$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \left\{ K + \sum_{i:h(x_i) \neq y_i} w_{t,i} (e^C - e^{-C}) \right\}$$

$K := \sum_{i=1}^n w_{t,i} e^{-\alpha_i}$ is a constant

$$= \operatorname{argmin}_{h \in \mathcal{H}} \left\{ (e^C - e^{-C}) \sum_{i:h(x_i) \neq y_i} w_{t,i} \right\}$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \sum_{i:h(x_i) \neq y_i} w_{t,i}$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} \frac{1}{\sum_{j=1}^n w_{t,j}} \sum_{i:h(x_i) \neq y_i} w_{t,i}$$

$\frac{1}{\sum_{j=1}^n w_{t,j}}$ is a constant

$$= \operatorname{argmin}_{h \in \mathcal{H}} \sum_{i:h(x_i) \neq y_i} \frac{w_{t,i}}{\sum_{j=1}^n w_{t,j}}$$

$$= \operatorname{argmin}_{h \in \mathcal{H}} P_{i \sim \mathcal{D}_t}(y_i \neq h(x_i))$$

See Lemma 1

□

Lemma 1

$$P_{i \sim \mathcal{D}_t}(y_i \neq h(x_i)) = \sum_{i: h(x_i) \neq y_i} \frac{w_{t,i}}{\sum_{j=1}^n w_{t,j}}$$

where

$$w_{t,i} := e^{-y_i H_{t-1}(x_i)}$$

Proof:

First, we show that

$$\mathcal{D}_t(i) = \frac{w_{t,i}}{\sum_{j=1}^n w_{t,j}} \tag{4}$$

We show this fact by induction. First, we prove the base case:

$$\begin{aligned} \frac{w_{1,i}}{\sum_{j=1}^n w_{1,j}} &= \frac{e^{-y_i H_0(x_i)}}{\sum_{j=1}^n e^{-y_j H_0(x_j)}} \\ &= \frac{1}{n} && \text{because } H_0(x_i) = 0 \\ &= \mathcal{D}_1(i) \text{ for all } i \end{aligned}$$

Next, we need to prove the inductive step. That is, we prove that

$$\mathcal{D}_t(i) = \frac{w_{t,i}}{\sum_{j=1}^n w_{t,j}} \implies \mathcal{D}_{t+1}(i) = \frac{w_{t+1,i}}{\sum_{j=1}^n w_{t+1,j}}$$

This is proven as follows:

$$\begin{aligned}
\mathcal{D}_{t+1}(i) &:= \frac{\mathcal{D}_t(i) e^{-\alpha_t y_i h_t(x_i)}}{\sum_{j=1}^n \mathcal{D}_t(j) e^{-\alpha_t y_j h_t(x_j)}} && \text{by Equation 3} \\
&= \frac{\frac{w_{t,i}}{\sum_{j=1}^n w_{t,j}} e^{-\alpha_t y_i h_t(x_i)}}{\sum_{j=1}^n \frac{w_{t,j}}{\sum_{k=1}^n w_{t,k}} e^{-\alpha_t y_j h_t(x_j)}} && \text{by the inductive hypothesis} \\
&= \frac{\frac{e^{-y_i H_{t-1}(x_i)}}{\sum_{j=1}^n e^{-y_j H_{t-1}(x_j)}} e^{-\alpha_t y_i h_t(x_i)}}{\sum_{j=1}^n \frac{e^{-y_j H_{t-1}(x_j)}}{\sum_{k=1}^n e^{-y_k H_{t-1}(x_k)}} e^{-\alpha_t y_j h_t(x_j)}} && \text{by the fact that } w_{t,i} := e^{-y_i H_{t-1}(x_i)} \\
&= \frac{\frac{1}{\sum_{j=1}^n e^{-y_j H_{t-1}(x_j)}} e^{-y_i H_{t-1}(x_i)} e^{-\alpha_t y_i h_t(x_i)}}{\frac{1}{\sum_{k=1}^n e^{-y_k H_{t-1}(x_k)}} \sum_{j=1}^n e^{-y_j H_{t-1}(x_j)} e^{-\alpha_t y_j h_t(x_j)}} \\
&= \frac{e^{-y_i H_{t-1}(x_i) - \alpha_t y_i h_t(x_i)}}{\sum_{j=1}^n e^{-y_j H_{t-1}(x_j) - \alpha_t y_j h_t(x_j)}} \\
&= \frac{e^{-y_i H_t(x_i)}}{\sum_{j=1}^n e^{-y_j H_t(x_j)}} \\
&= \frac{w_{t+1,i}}{\sum_{j=1}^n w_{t+1,j}}
\end{aligned}$$

Now that we have proven Equation 4, it follows that

$$\begin{aligned}
\sum_{i:h(x_i) \neq y_i} \frac{w_{t,i}}{\sum_{j=1}^n w_{t,j}} &= \sum_{i:h(x_i) \neq y_i} \mathcal{D}_t(x_i) \\
&= P_{i \sim \mathcal{D}_t}(y_i \neq h_t(x_i))
\end{aligned}$$

□

Theorem 2 *The choice of α_t under AdaBoost,*

$$\alpha_t := \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right)$$

where

$$\epsilon_t := P_{i \sim \mathcal{D}_t}(y_i \neq h_t(x_i))$$

, minimizes the exponential-loss of H_t over the training set. That is,

$$\alpha_t = \underset{\alpha}{\operatorname{argmin}} L_S(H_{t-1} + \alpha h_t)$$

Proof:

Our goal is to solve

$$\begin{aligned} \alpha_t &:= \underset{\alpha}{\operatorname{argmin}} L_S(H_{t-1} + \alpha h_t) \\ &= \underset{\alpha}{\operatorname{argmin}} \left\{ \left(\sum_{i:h(x_i) \neq y_i} w_{t,i} \right) e^\alpha + \left(\sum_{i:h(x_i) = y_i} w_{t,i} \right) e^{-\alpha} \right\} \end{aligned}$$

To do so, set the derivative of the function in the argmin to zero and solve for α (the function is convex, though we don't prove it here):

$$\begin{aligned} \frac{d}{d\alpha} \left\{ \left(\sum_{i:h(x_i) \neq y_i} w_{t,i} \right) e^\alpha + \left(\sum_{i:h(x_i) = y_i} w_{t,i} \right) e^{-\alpha} \right\} &= 0 \\ \Rightarrow \left(\sum_{i:h(x_i) \neq y_i} w_{t,i} \right) e^\alpha - \left(\sum_{i:h(x_i) = y_i} w_{t,i} \right) e^{-\alpha} &= 0 \\ \Rightarrow e^{2\alpha} &= -\frac{\sum_{i:h(x_i) \neq y_i} w_{t,i}}{\sum_{i:h(x_i) = y_i} w_{t,i}} \\ \Rightarrow 2\alpha &= \ln \left(-\frac{\sum_{i:h(x_i) \neq y_i} w_{t,i}}{\sum_{i:h(x_i) = y_i} w_{t,i}} \right) \\ \Rightarrow \alpha &= \frac{1}{2} \ln \left(\frac{\sum_{i:h(x_i) = y_i} w_{t,i}}{\sum_{i:h(x_i) \neq y_i} w_{t,i}} \right) \\ \Rightarrow \alpha &= \frac{1}{2} \ln \left(\frac{\sum_{i=1}^n w_{t,i} - \sum_{i:h(x_i) \neq y_i} w_{t,i}}{\sum_{i:h(x_i) \neq y_i} w_{t,i}} \right) \\ \Rightarrow \alpha &= \frac{1}{2} \ln \left(\frac{\frac{1}{\sum_{i=1}^n w_{t,i}} \sum_{i=1}^n w_{t,i} - \sum_{i:h(x_i) \neq y_i} w_{t,i}}{\frac{1}{\sum_{i=1}^n w_{t,i}} \sum_{i:h(x_i) \neq y_i} w_{t,i}}} \right) \\ \Rightarrow \alpha &= \frac{1}{2} \ln \left(\frac{1 - \frac{\sum_{i:h(x_i) \neq y_i} w_{t,i}}{\sum_{i=1}^n w_{t,i}}}{\frac{\sum_{i:h(x_i) \neq y_i} w_{t,i}}{\sum_{i=1}^n w_{t,i}}} \right) \\ \Rightarrow \alpha &= \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right) \end{aligned}$$

□

Bibliography

- [1] Y. Freund and R.E. Schapire. A decision-theoretic generalization of on-line learning and an application to boosting. *Journal of Computer and System Sciences*, 1996.